

services executing on heterogeneous clusters. When a new request comes, a heuristic for multidimensional bin packing is used to find a server to allocate the request. If a server cannot be found, a new machine is turned on and all requests are re-allocated. The work in [7] aims at serving web-applications on homogeneous clusters according to utility function. In work of [9], they investigate the problem of minimizing mean response time of web-applications on heterogeneous clusters. In this work the optimal power allocation is determined based on queuing theoretical model.

Recently emerged Cloud Computing paradigm leverages virtualization of computer resources and allows to achieve more efficient allocation of workload in terms of higher resource utilization as well as decreased power consumption. The work in [14] is targeted on minimizing both power consumption and SLA violations for online services on virtualized datacenters using a limited look-ahead control. The *pMapper* architecture is also proposed in [24, 23] to solve the same problem with consideration of migration cost. In the work [6], they present several techniques for addressing the sharing aware VM allocation problem. Hypervisor distributes resources among VMs according to a sharing based mechanism, when the minimum and maximum amount of resources that can be allocated to a VM is specified.

In addition, many studies have focused on power-aware real-time applications on clusters. A QoS-aware power management scheme is presented by combining cluster-wide (On/Off) and local (DVS) power management techniques in the context of heterogeneous clusters [18]. The front-end manager decides which servers are turned on or off for a given system load, while local PM reduces power consumption using DVS scheme. In [26], a threshold-based method is proposed for efficient power management of heterogeneous soft real-time clusters as well as the offline mathematical analysis of determining the threshold. In addition, power-aware algorithms are investigated for scheduling of real-time bag-of-tasks applications with deadline constraints on homogeneous clusters [13].

Considerable amount of work have been done in the area of power-efficient computing, but few of them deal with power-aware scheduling of real-time applications in Cloud Computing environments. This work investigates the problem of provisioning Cloud resources for real-time services in order to minimize power consumption by modeling real-time virtual machine requirement and using DVFS techniques.

3. FRAMEWORK

3.1 Real-time Service Model

A usual real-time service such as financial analysis, distributed databases, or image processing, consists of multiple real-time applications or subtasks. As long as a group of applications for a given real-time service meet all their deadlines, the service accomplishes the quality of service agreed with users. A real-time service is defined by $\{\tau_i(r_i, c_i, d_i, p_i, f_i) | i = 1, \dots, n\}$, where n is the number of subtasks. Each real-time subtask τ_i is defined by the following parameters.

- r_i : release time
- c_i : worst-case execution time
- d_i : relative deadline
- p_i : period
- f_i : finish time

A real-time application can be started at time r_i and requires the worst-case execution time c_i . In order to accomplish the application's objective, it should be completed by the time $r_i + d_i$ after released. Also, p_i specifies its periodicity so that the task releases a job of c_i computation time at time $(r_i + kp_i)$, and should be finished by $r_i + kp_i + d_i$ ($k = 0, 1, \dots$). In case of non-periodic application, p_i is set to zero. We also consider duration or finish time, f_i , since a user cannot access a cloud computing resource forever, although a periodic real-time task in embedded system assumes an infinite sequence.

This group of sub-tasks of a real-time service is developed and launched on a specific run-time platform including middlewares, operating systems, and so on. The cloud computing environment is a suitable solution for real-time services by leveraging *virtualization*. When users request their requirements for real-time services to the cloud computing environment, appropriate virtual machines are allocated for executing those services.

3.2 Real-time Virtual Machine Model

Cloud resource brokers take a role in finding Cloud resources or virtual machines for real-time services requested by users. In this paper, we define *RT-VM (Real-Time Virtual Machine)* as the requirement of a virtual machine for providing a real-time service. RT-VM V_i of a real-time service includes three parameters u_i , m_i , and d_i .

- u_i : utilization of real-time applications
- m_i : MIPS (Million Instructions Per Second) rate of the based virtual machine
- d_i : lifetime or deadline

The service is developed and launched on a specific platform or infrastructure (e.g. 1GHz-Linux machine). We select the MIPS rate, m_i , for the specification of the base machine. For a given set of real-time applications, we can analyze the required CPU utilization u_i on the base machine. Thus, the above requirement implies that the real-time service is guaranteed when the allocated virtual machine keeps providing $u_i \times m_i$ amount of processing capacity by the deadline d_i . This real-time service on virtualized cloud resource is achieved by *compositional real-time computing* and *real-time virtual machine* techniques.

The compositional or hierarchical real-time framework [8, 20] enables a group of real-time applications to be a single real-time resource requirement to the upper layer of real-time environments. Thus, we assume that a RT-VM V_i is defined from multiple real-time applications, $\{\tau_k(r_k, w_k, d_k, p_k, f_k) | k = 1, \dots, n\}$, of the service by using compositional real-time technique. Thus, VM provisioner in Clouds maps virtual machines for the service, not for individual applications. Furthermore, recent work on implementing real-time virtual machines [25, 28] assures real-time services (e.g. real-time CPU allocation, real-time I/O) of a virtual machine. This paper focuses on how to provision virtual machines to a given RT-VM request with consideration of power consumption by leveraging these techniques.

3.3 Real-time Cloud Service Framework

In this subsection, we describe the real-time cloud service framework based on real-time virtual machine model. As shown in Figure 1, the steps for a real-time service are as follows.

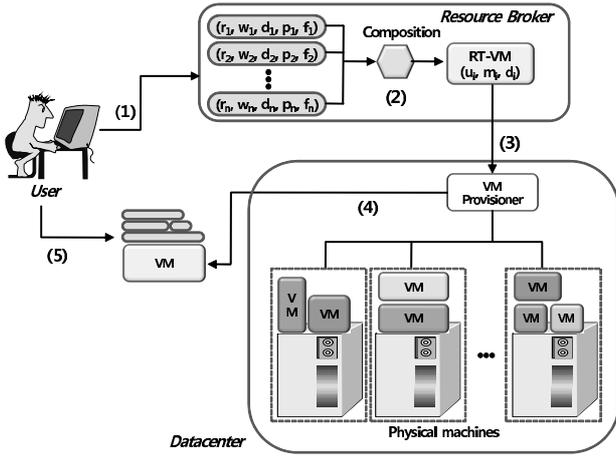


Figure 1: Framework

- (1) *Requesting a virtual platform:* A user who wants to launch a real-time service submits all the information about real-time applications to the broker.
- (2) *Generating the RT-VM from real-time applications:* The resource broker first analyzes the submitted real-time applications and generates one RT-VM request, $V_i = (u_i, m_i, d_i)$.
- (3) *Requesting a real-time virtual machine:* The broker requests a virtual machine for RT-VM V_i to the VM provisioner in the cloud computing.
- (4) *Mapping the physical processors:* The VM provisioner finds appropriate processing elements which meet the V_i requirement. And then, it provides the VM to the user.
- (5) *Executing the real-time applications:* The user finally launches and executes real-time applications on the provided VM.

3.4 Energy model

The most part of power consumption in datacenters comes from computation processing, disk storage, network, and cooling systems. This paper focuses on CPU power saving in terms of virtual machine provisioning in the cloud computing.

The main power consumption in CMOS circuits is composed of dynamic and static power. We only consider the dynamic power dissipation because it is more dominating factor in the total power consumption [16]. And, datacenters can increase their profit by reducing dynamic power consumption. The dynamic energy consumption by an application is proportional to V_{dd}^2 and f , where V_{dd} is the supply voltage and f is the frequency [4]. Since the frequency is usually in proportion to the supply voltage, the dynamic power consumption of processor is given by

$$P = C \cdot f^3$$

where C is a proportional coefficient. Let us consider an application of t execution time at the frequency f_{max} of the processor. If the processor runs at f frequency level ($0 <$

$f \leq f_{max}$), the execution time is defined by $t/\frac{f}{f_{max}}$. Thus, the dynamic energy consumption during the task execution is defined by Equation (1).

$$E = \int_0^{t/\frac{f}{f_{max}}} P = C \cdot t \cdot f_{max} \cdot f^2 = \alpha \cdot t \cdot S^2 \quad (1)$$

where α is a coefficient and S is the associated processor speed related to the frequency f ($S = f/f_{max}$). The DVFS (Dynamic Voltage Frequency Scaling) scheme reduces the dynamic energy consumption by decreasing the supplying voltage and frequency, which results in slowdown of the execution time. We assume that each PE (Processing Element) p in a datacenter can adjust its processor frequency from f_p^{min} to f_p^{max} continuously. The associated processor speed S with each frequency f is defined by f/f_{max} , which follows that $f_p^{min}/f_p^{max} < S \leq 1$.

4. POWER-AWARE RT CLOUD SERVICE

4.1 Problem Description

Let us consider a physical machine with one PE of 2400 MIPS and a set of RT-VMs, $\{V_1(0.2, 1000, 10), V_2(0.8, 500, 15), V_3(0.5, 1200, 20)\}$, as an example. V_1 requires the utilization 20% on 1000-MIPS machine by the deadline 10 sec. Similarly, V_2 and V_3 require 80% and 50% of 500-MIPS and 1200-MIPS machines by 15 and 20 seconds, respectively. Figure 2(a) shows the proportional sharing scheduling result of three VMs under the maximum processor capacity. The proportional share of V_i is defined by $m_i \times u_i / \sum_{j=1}^3 (m_j \times u_j)$. Three RT-VMs share the processor capacity in proportion to their required MIPS rates, $m_i \times u_i$, and finish before the deadlines. The total energy consumption is 8.34 ($= 1 \times 8.34 \times 1.0^2$) by Equation (1) under the assumption of $\alpha = 1$.

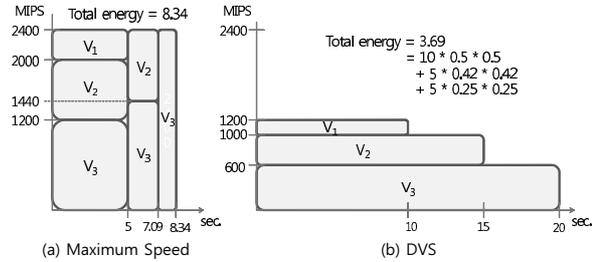


Figure 2: Proportional sharing of VM provisioning and energy consumption ($\alpha = 1$)

The energy consumption can be reduced by combining DVS and proportional sharing scheduling. As shown in Figure 2(b), the minimum required processor capacity is allocated to each virtual machine, so that the processor dynamically adjust its speed to $\sum (m_j \times u_j) / 2400$. The total energy consumption of DVS scheme is 3.69 ($= 10 \times 0.5^2 + 5 \times 0.42^2 + 5 \times 0.25^2$). Thus, DVS scheme can reduce much energy compared to the maximum-speed static scheme.

However, there are tradeoffs in dynamic scaling of processor speed in on-line real-time cloud computing. Operation in higher speed processor can accept more RT-VMs with more

energy consumption. On the contrary, scaling down to lower processor speed consumes less energy with lower acceptance. For example, let us assume that a new RT-VM V_4 (0.8, 2000, 10) is requested at time 10. Figure 2(a) accepts V_4 since the processor is idle at time 10, while DVS scheme of Figure 2(b) cannot provision it due to lack of processor capacity.

Datacenters can increase their profit by provisioning more virtual machines to users. In addition, reducing energy consumption also increases profit by reducing the cost for clouding service. Thus, this paper provides several schemes on power-aware provisioning of real-time virtual machines for the purpose of maximizing profits of cloud computing datacenters.

We use proportional sharing scheduling for scheduling multiple virtual machines on a processor. The proportional sharing scheduling is simple but guarantees the real-time services of RT-VMs if the total required MIPS rate is less than or equal to the processor capacity. Furthermore, it can be easily implemented. For example, the default scheduling in Xen Hypervisor [17] is *Credit scheduler* which is based on credit value set by weight of each VM. The VMM (Virtual Machine Monitor) can dynamically adjust credit values of VMs according their required MIPS rates in order to support the proportional sharing scheme.

Before explaining the VM provisioning, we define the remaining service time, w_i , of V_i . The initial value of w_i is defined by $u_i \times m_i \times (d_i - t_s)$, at its submission time t_s . If V_i is provided with q_i MIPS rate for the period t_p , w_i is decreased by $q_i \times t_p$. For instance, Table 1 shows the remaining service times of three RT-VMs at the time of proportional share change of Figure 2(a). V_i finishes its service when w_i becomes zero.

Table 1: Remaining service times of Figure 2(a)

	$t = 0$		$t = 5$		$t = 7.09$		$t = 8.34$	
	w_i	ST_i [0, 5]	w_i	ST_i [5, 7.09]	w_i	ST_i [7.09, 8.34]	w_i	ST_i
V_1	2000	2000	0	-	-	-	-	-
V_2	6000	4000	2000	2000	0	-	-	-
V_3	12000	6000	6000	3010	2990	2990	0	-

($ST_i[t_1, t_2]$: The service time of V_i from t_1 to t_2)

4.2 DVS-enabled RT-VM Provisioning

When a datacenter receives a RT-VM request from a resource broker, it returns the price of providing the RT-VM service if it can provide real-time virtual machines for that request. The broker selects the minimum-price virtual machine among available datacenters. Thus, the provisioning policy in this paper is to select the processing element with the minimum price for the sake of users. Figure 3 shows the pseudo-algorithm of provisioning the virtual machine for a given RT-VM request.

For a given RT-VM $V_i(u_i, m_i, d_i)$, the datacenter checks the schedulability of V_i on the processing element PE_k of Q_k MIPS rate. Suppose that the current running RT-VMs on the processing element PE_k at time t is known as $T_k = \{V_j(u_j, m_j, d_j) | j = 1, \dots, n_k\}$. And the remaining service time of V_j at time t is denoted as w_j . Then, the schedulability is guaranteed if it satisfies Equation (2). Since $w_j/(d_j - t)$ is the minimum MIPS rate for V_j by its deadline d_j , Equat-

Algorithm Min-Price RT-VM Provisioning (V_i)

```

1:  $VM \leftarrow null$ ;
2:  $alloc \leftarrow -1$ ;
3:  $e_{min} \leftarrow MAX\_VALUE$ ;
4:  $price_{min} \leftarrow MAX\_VALUE$ ;
5: for  $k$  from 1 to  $N$  do
6:   if ( $u_i \times m_i + \sum_{j=1}^{n_k} \frac{w_j}{d_j - t} \leq Q_k$ ) then
7:      $e_k \leftarrow energy\_estimate(PE_k, V_i)$ ;
8:      $price_k \leftarrow price$  for the RT-VM  $V_i$  in  $PE_k$ ;
9:     if  $price_k < price_{min}$  or
10:    ( $price_k = price_{min}$  and  $e_k < e_{min}$ ) then
11:       $price_{min} \leftarrow price_k$ ;
12:       $e_{min} \leftarrow e_k$ ;
13:       $alloc \leftarrow k$ ;
14:   endif
15: endif
16: endfor
17: if  $alloc \neq -1$  then
18:    $VM \leftarrow create\_VM(PE_{alloc}, V_i)$ ;
19: endif
20: return  $VM$ ;

```

Figure 3: Min-Price RT-VM Provisioning

tion (2) means that total summation of all the required MIPS rates including the new RT-VM V_i is less than the processor capacity Q_k .

$$u_i \times m_i + \sum_{j=1}^{n_k} \frac{w_j}{d_j - t} \leq Q_k \quad (2)$$

If PE_k is able to schedule V_i , it estimates energy and price of provisioning (line 7, 8). Since the provisioning policy is to provide lower price to users, the algorithm finds the minimum-price processor. For the same price, less energy is preferable because it produces higher profit (line 9-14). Finally, a virtual machine is mapped on PE_{alloc} if RT-VM V_i is schedulable on the datacenter.

When a user launches the service on the VM, the resource provider provision the VM using DVS schemes to reduce the power consumption. We propose three power-aware VM provisioning schemes: *Lowest-DVS*, δ -*Advanced-DVS*, and *Adaptive-DVS*. The following subsections describe them.

4.2.1 Lowest-DVS for VM Provisioning

This scheme adjusts the processor speed to the lowest level at which RT-VMs meet their deadlines. That is, each RT-VM V_i executes its service at the required MIPS rate, as shown in Figure 2(b). It consumes the lowest energy in the case that the RT-VM arrival rate is low enough to accept all the requests.

4.2.2 δ -Advanced-DVS for VM Provisioning

In order to overcome the low service acceptance rate of Lowest-DVS scheme, this scheme over-scales more up to $\delta\%$ of the required MIPS rate for current RT-VMs. Thus, it operates the processor speed $\delta\%$ faster in order to increase the possibility of accepting coming RT-VM requests. The processor scale s is adjusted as in Equation (3) at time t for a given RT-VM set T_k . The proportional share of each VM

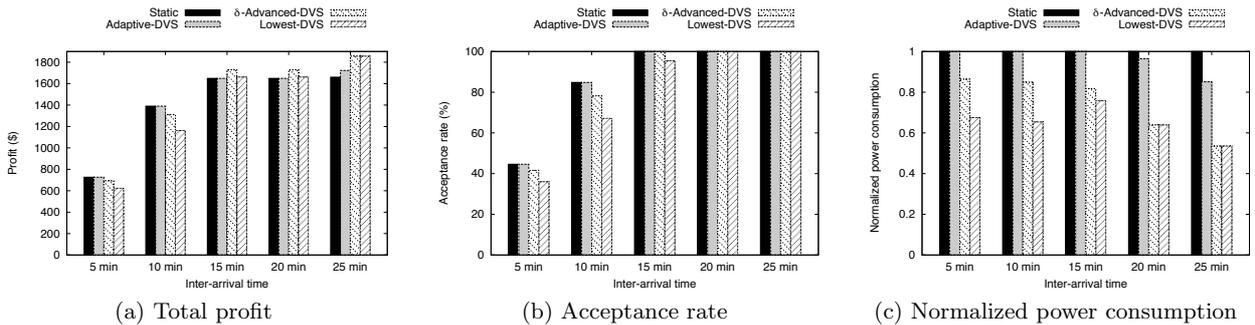


Figure 4: Simulation results

is in proportional to $w_i/(d_i - t)$.

$$s = \min \left\{ 1, \left(1 + \frac{\delta}{100}\right) \times \frac{1}{Q_k} \sum_{V_i \in T_k} \frac{w_i}{d_i - t} \right\} \quad (3)$$

The value of $\delta\%$ is predefined in the systems according to the system load. Throughout the simulation results in Section 5, we analyze the impact of δ .

4.2.3 Adaptive-DVS for VM Provisioning

When the RT-VM arrival rate and its service time are known in advance, we can analyze an optimal scale. Let us consider the $M/M/1$ queuing model with arrival rate λ and service rate μ . If the processor speed scale is set to s , then the average response time, RT , is given by $RT = 1/(s\mu - \lambda)$ by $M/M/1$ queuing model. And, the response time should be less than or equal to the average deadline, d , in order to meet their real-time services ($1/(s\mu - \lambda) \leq d$). Thus, an optimal scale, s^* , to reduce the power-consumption is given by Equation (4).

$$s^* = \frac{1}{\mu} \left(\lambda + \frac{1}{d} \right) \quad (4)$$

Adaptive-DVS scheme manages the average arrival rate $\hat{\lambda}$, the average service rate $\hat{\mu}$, and the average deadline \hat{d} for the last h service requests (e.g. $h = 10$). And, it adjusts the processor scale s as in Equation (5) at time t for a given RT-VM set T_k .

$$s = \max \left\{ \min \left\{ 1, \frac{1}{\hat{\mu}} \left(\hat{\lambda} + \frac{1}{\hat{d}} \right) \right\}, \frac{1}{Q_k} \sum_{V_i \in T_k} \frac{w_i}{d_i - t} \right\} \quad (5)$$

In Equation (5), the optimal scale is calculated by Equation (4) not greater than one. Since it should be greater than the minimum required utilization of the current RT-VMs on the processor, we select the maximum between two values. So, the processor adjusts the processor speed by Equation (5) when a new RT-VM is provided or an existing one finishes its service.

5. SIMULATION RESULTS

We evaluate simulations of power-aware real-time services using the CloudSim toolkit [5] with additional development of power-awareness capability. We create a datacenter with

four machines with 16 DVS-enabled processors of which characteristics are shown in Table 2.

Table 2: Characteristics of datacenter

	# of PEs	MIPS of PE	DVS level	α (10^{-3})
Machine 0	4	1,800	[0, 1.0]	2.92
Machine 1	4	2,400	[0, 1.0]	4.08
Machine 2	4	3,000	[0, 1.0]	5.37
Machine 3	4	3,400	[0, 1.0]	6.21

The price model in the simulations follows the Amazon EC2 Standard small (default) instance type [2], so that the unit price per hour is given by \$0.10. We use the cost function as the power consumption of each machine in Table 2.

In the simulations, we generate 500 RT-VMs. The total service amount (w_i) of a RT-VM is randomly selected from 2,400 GIs (10^3 MIs) to 3,600 GIs. The deadline is selected from 10 to 30 minutes more than the execution time based on 1000-MIPS machine. The interarrival time between two RT-VMs follows a Poisson distribution. We simulate various interarrival times.

Figure 4(a) shows the total profits of each scheme according to interarrival time. **Static** does not use DVS so that it runs virtual machines at the maximum processor speed. In **δ -Advanced-DVS** we fix δ as 15%. In higher arrival rates, **Static** produces more profits since it accepts more RT-VMs. **Adaptive-DVS** gives no less profit than **Static**, while other DVS schemes show more profit in lower arrival rates due to lower energy consumption.

Figure 4 (b) and (c) show the RT-VM acceptance rate and the normalized power consumption compare to **Static**, respectively. The acceptance rate of **Adaptive-DVS** is close to **Static** but reduces much energy in case of low arrival rate. **δ -Advanced-DVS** shows more acceptance rate with similar energy consumption compared to **Lowest-DVS**. Generally, **δ -Advanced-DVS** shows the best performance in terms of profit per consumed power since the amount of scaling up is controlled automatically according to the system load. In case of **Adaptive-DVS**, its performance is limited by the simplified queueing model.

Next, we also vary the value of δ in order to analyze the impact of δ . As shown in Figure 5, higher δ shows better performance in higher arrival rate since it may accept more VMs. On the contrary, lower δ produces more profit in case of lower arrival rate. In the simulations, the system utiliza-

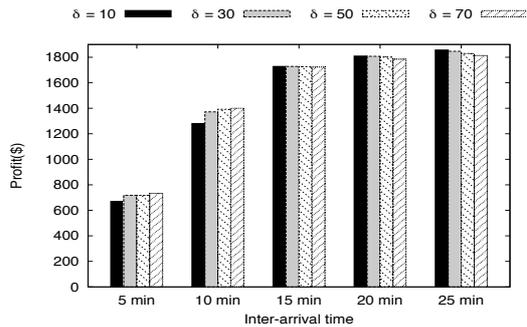


Figure 5: Impact of δ in δ -Advanced-DVS

tion is generally high regardless of arrival rates, so that δ has little impact on the profit.

6. CONCLUSIONS

In this paper, we have proposed a real-time Cloud service framework where each real-time service request is modeled as RT-VM in resource brokers. And then, we have investigated power-aware provisioning of virtual machines for real-time Cloud services. Simulation results show that datacenters can reduce power consumption and increase their profit using DVS schemes. The proposed adaptive schemes, Adaptive-DVS and δ -Advanced-DVS, show more profit with less power consumption regardless of system load.

Our immediate future work includes more analysis and improvement of the proposed adaptive schemes. For example, we will compare them with other approaches, such as bin packing or linear programming, and analyze the impact in the cooling systems. We also plan to implement the proposed framework in Cloud broker and experiment it.

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